

IMCA-CAT

Getting to Know You

abbvie



Bristol-Myers Squibb



MERCK

Be well



NOVARTIS



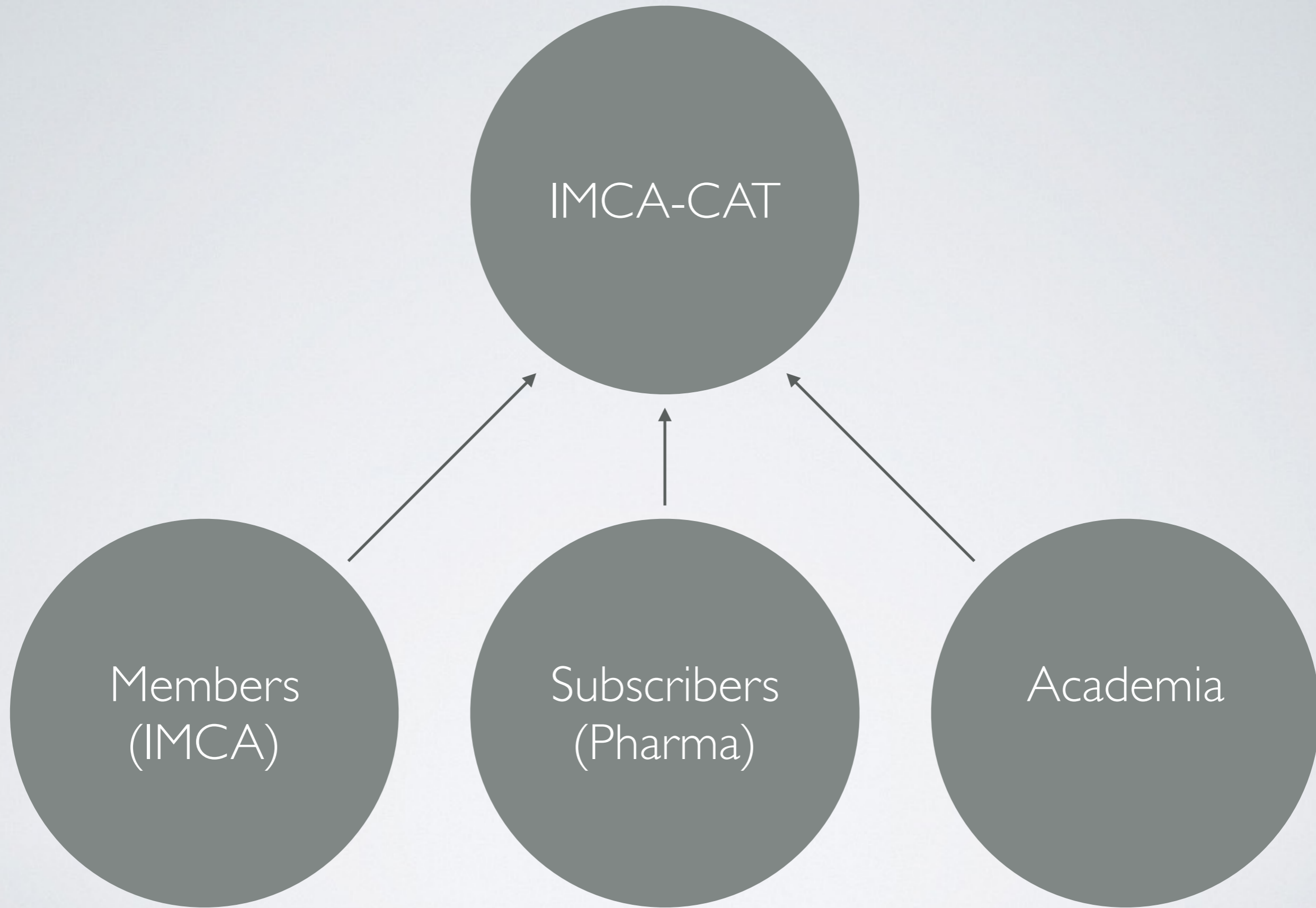
The diagram features a dark gray inverted triangle at the top with the text 'IMCA' centered inside it. Below the triangle are two dark gray rectangular boxes, one on the left and one on the right, containing the text 'High-Quality' and 'High-Throughput' respectively. The entire graphic is set against a light gray background.

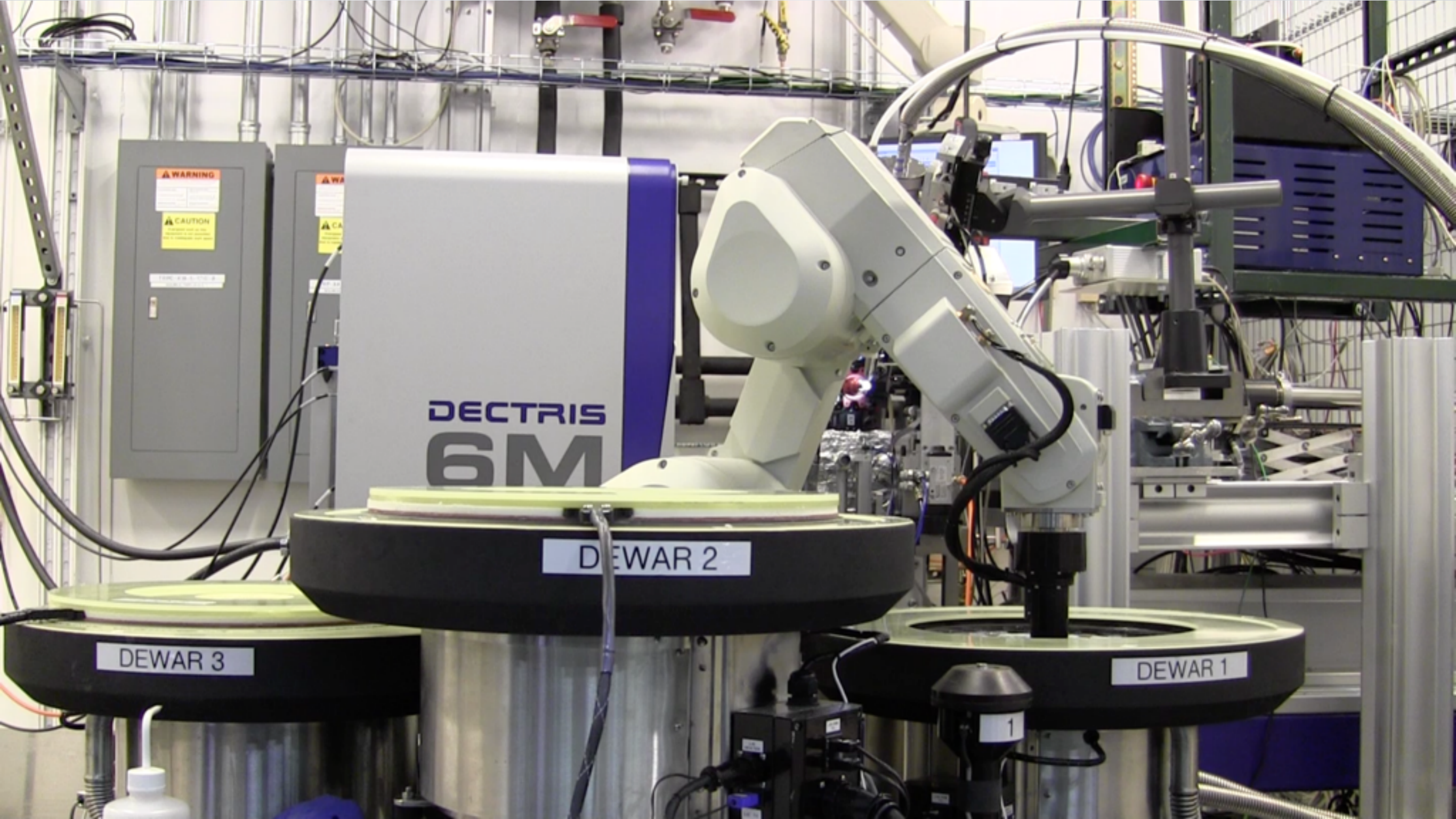
IMCA

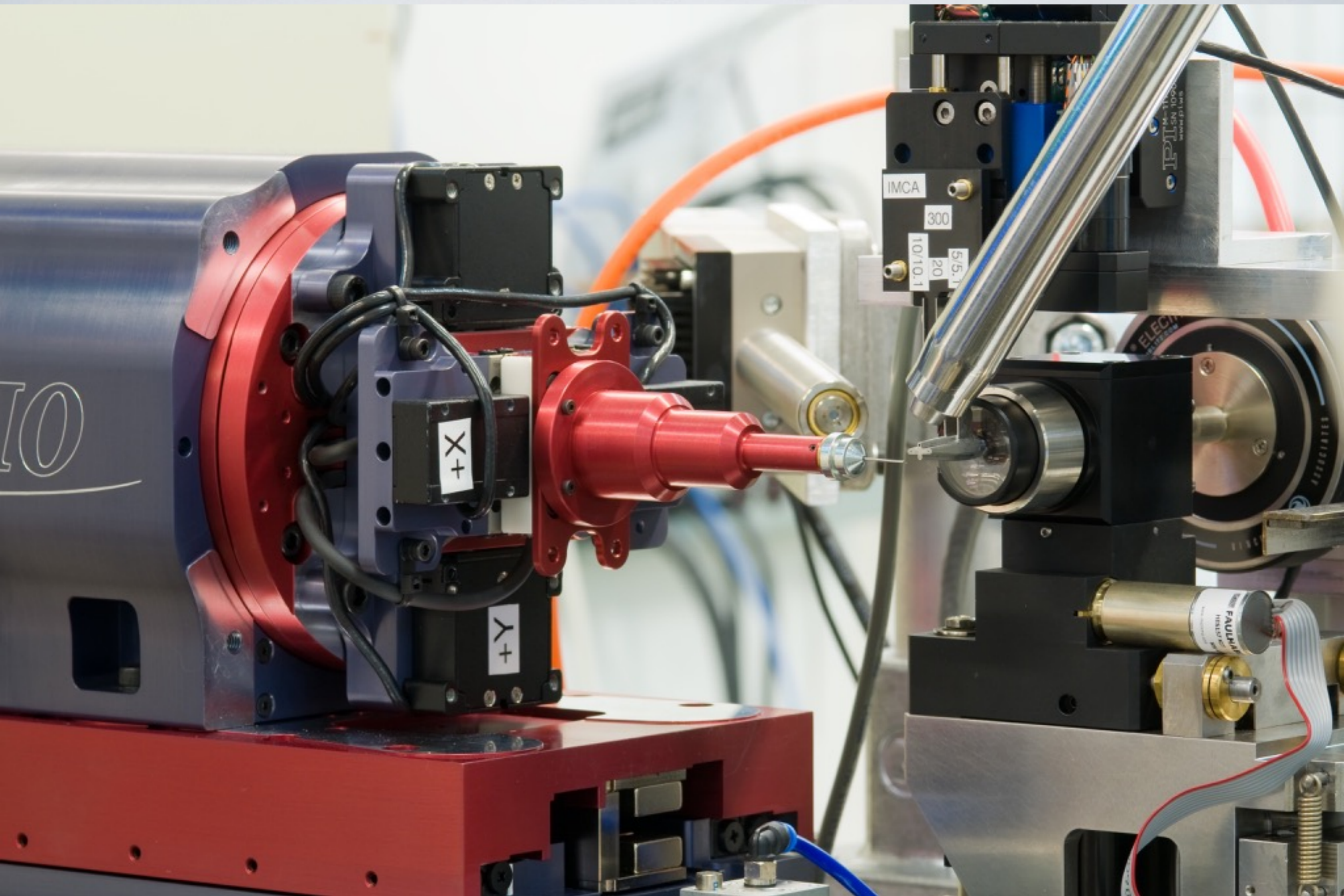
High-Quality

High-Throughput









Small-crystal

LCP

SAD

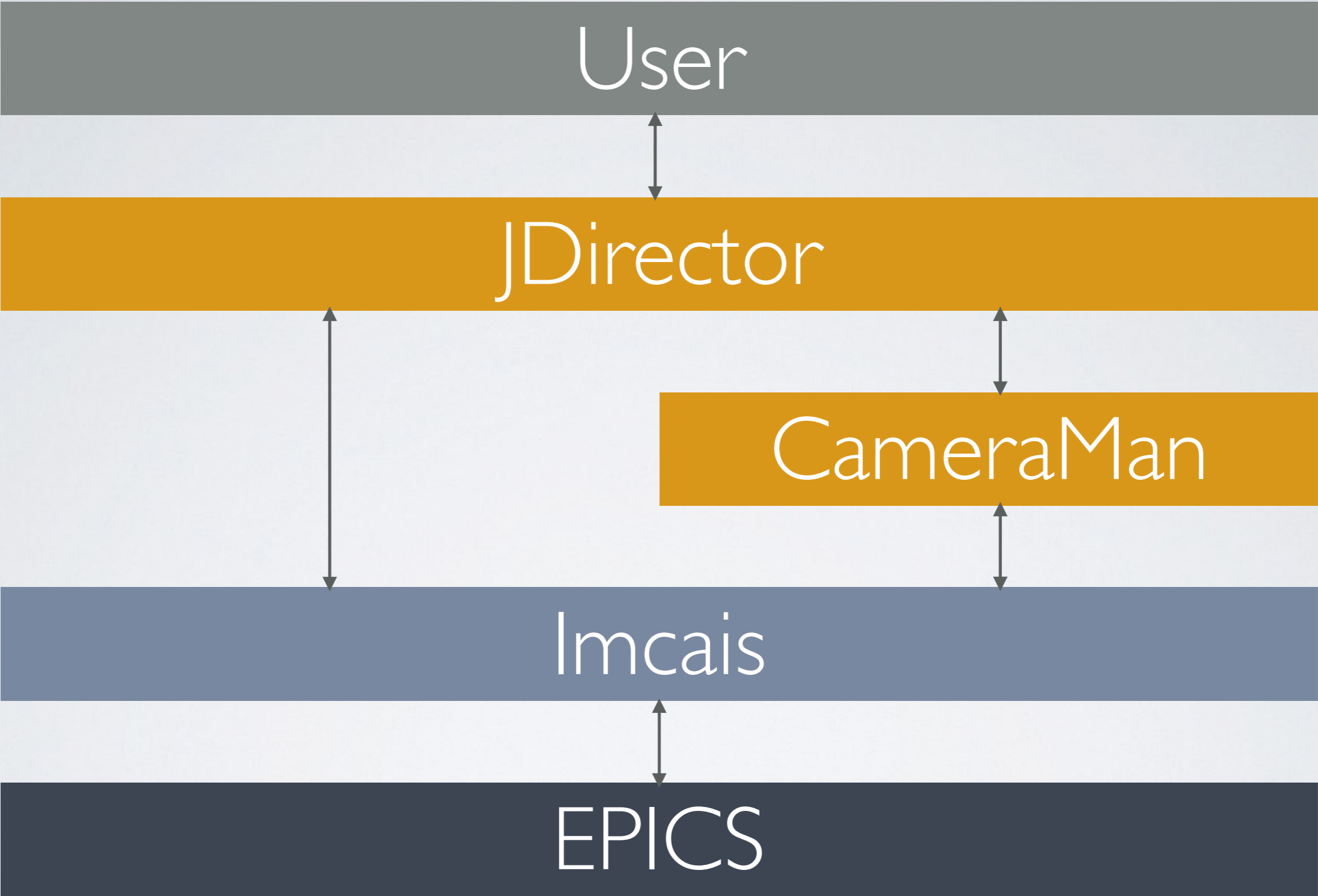
MAD

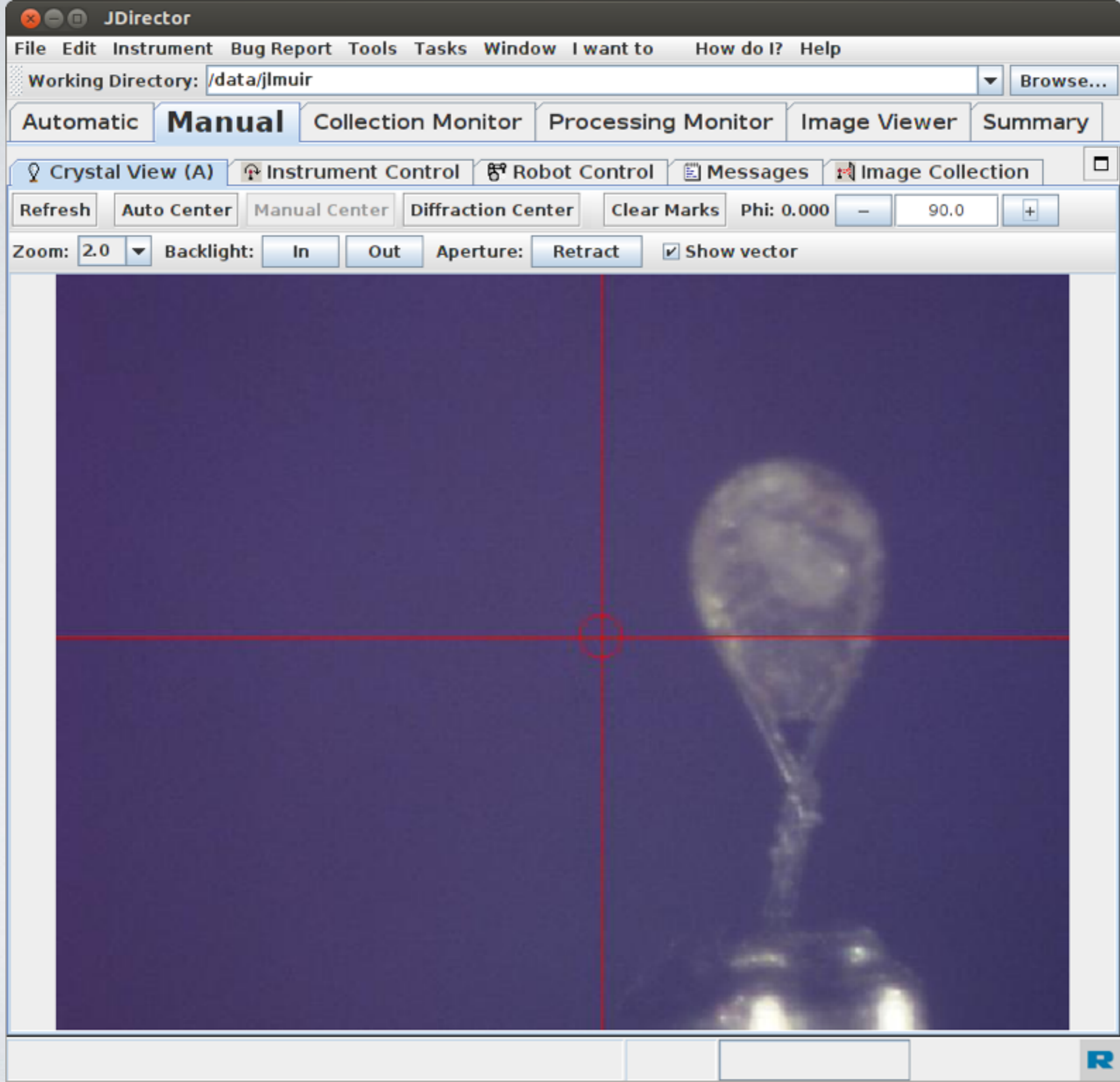
Routine high-throughput

On-Site

Remote

Mail-In
(Members)





Working Directory: /data/jlmuir/test

Browse...

Automatic **Manual** Collection Monitor Processing Monitor Image Viewer Summary

Messages Image Collection Instrument Control Crystal View (A) Robot Control

Enter scan parameters

Scan 1

Load Scans...

Add copy

Remove

Image width: 0.25 deg

Image step: 0.25 deg

Start angle: 0.0 deg

End angle: 0.25 deg

Number of images: 1

Start number: 101 - 101

Exposure time: 0.25 sec

Detector 2θ: 0 deg

Detector distance: 250.0 mm

Scan along vector

Vector start (X, Y, Z): μm

Vector end (X, Y, Z): μm

Vector length: μm

Number of points: 2

Scan in inverse wedge mode

Wedge width: 10.00 deg

Wavelength: 1.000000 Å

Transmission: 5.8 %

Aperture: 300 μm

Use Current Position

Use Current Position

Scan template: Working directory Image_????.img

Expansion: /data/jlmuir/test/Image_????.img

Status	Image width (°)	Image step (°)	Start angle (°)	End angle (°)	Number of images	Start number	Expose time (sec)	φ (°)	Z (mm)	2θ (°)	Distance (mm)
⚠	0.25	0.25	0.0	0.25	1	101	0.25	----	0	0	250.0

Stop after image

Load scans...

Save scans...

Collect

Working Directory: /data/jlmuir/test Browse...

Automatic Manual Collection Monitor Processing Monitor Image Viewer Summary

Messages Image Collection State Robot Control Crystal View (A)

Job Control Sample one-image.rcp - Edit Recipe

Stop After Sam... Dismount At E...

Jobs

Name	Type	Status	Directory	Robot Used
<input type="checkbox"/> Job10	Recipe (with Robot Control)		/data/jlmuir/test/job10	<input checked="" type="checkbox"/>

Job Editor (Job10)

Samples Follow-up Job

Position	Status	Recipe	Stored Center	Diffraction Center	Aperture	Transmission (%)	Distance (mm)
<input type="checkbox"/> 1_1_01			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_02			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_03			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_04			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_05			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_06			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_07			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_08			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_09			<input type="checkbox"/>	<input type="checkbox"/>			
<input type="checkbox"/> 1_1_10			<input type="checkbox"/>	<input type="checkbox"/>			

Fly-scan diffraction centering

Vector data collection

Fully automated data collection: 18.5 datasets/hr

Aaproc

Puck tracking system (Coming soon!)

LCP

In-situ plates

Multiple crystals per loop

Continuous translation data collection

Diffraction centering

Automated data processing pipeline

Puck/sample/experiment tracking/management/results system



Community